

The AQPI QPE System Architecture

The National Oceanic and Atmospheric Administration (NOAA) and collaborating partners are building an Advanced Quantitative Precipitation Information (AQPI) system aimed at improving monitoring and forecasting of precipitation, streamflow, and coastal flooding in the San Francisco Bay Area.

As part of the AQPI program, high-frequency (i.e., X-band) highresolution gap-filling radars are being deployed over the Bay Area to augment observations from the NEXRAD network, improve quantitative precipitation estimates (QPE), and resolve the detailed precipitation microphysics (see **Poster A53L-3073** by Cifelli et al.).

This paper presents the integrated QPE system built upon the AQPI radar observations and existing NEXRAD product for seamless highresolution rainfall mapping over the entire Bay Area.



Fig. 2. Integrated AQPI radar QPE system.

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Integrating Multi-scale Data for Seamless QPE in the AQPI System

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Bias Correction of NEXRAD Rainfall Product

T(s,t): gauge measurement (precipitation "truth") at site s and time t R(s,t): radar rainfall estimate at site s and time t; Ideally, the bias corrected radar estimate should be close to T(s, t). The conditional probability of T given that radar estimate R is available can be expressed as follows:

$P(T|R) \propto P(R|T)P(T)$

where P(T|R) is the posterior probability of T occurring given that R is true; P(R|T) is the likelihood of R occurring given that T is true; P(T) is the prior probability of T. In applications, it is reformulated in a continuous form: $f(T|R) \propto f(R|T)f(T)$

$R|T \sim D(\boldsymbol{\theta})$

where D stands for the conditional distribution of R|T derived from various distribution families, and $\theta = (\theta_1, \theta_2, \dots, \theta_n)$ indicates the associated collection of n distribution parameters. Each conditional distribution D can be expressed to incorporate the spatial and temporal covariates: $\theta \to g(\beta; T, \gamma)$, where g is the linked function; β represents the parameter set of the linked function; γ is the collection of covariates (i.e., radar rainfall estimates, and/or terrain and wind information).

The q-quantiles of the posterior predictive distribution of T^* is used to correct R^* , the radar estimates at the new site and/or time. The posterior distribution of T^* given R^* occurring is:



Fig. 3. Overall diagram of the Bayesian framework for NEXRAD QPE bias correction. For details, see Chen et al. (2019, Journal of Hydrometeorology)



- product using surface rain gauge measurements;
- Bay Area;

A Bayesian model is developed for bias correction of NEXRAD rainfall

An integrated QPE system is designed based on multi-scale data over the

The integrated QPE is being implemented into the real-time AQPI system.